Application Note: AN_SY8722A

High Efficiency, Flicker-free **MR16 LED Driver Preliminary Specification**

General Description

SY8722A is a high efficiency, flicker-free, MR16 LED driver which is powered by electronic transformer. The device integrates two DC/DC regulators. The first stage boosts the input voltage to a setting value and provides power supply for the second stage. The second stage regulates the LED current to the target value. With proprietary control scheme, the LED driver is compatible with most of commonly used electronic transformers. The high switching frequency allows the use of small size inductor and capacitor. The integrated low R_{DS(ON)} MOSFETs reduce the power loss. Along with compact SO8E package, SY8722A provides ideal solution for MR16 LED lighting.

Ordering Information



Ordering Number	Package type	Note
SY8722AFCC	SO8E	

Features

- Wide input range: 4-30V
- CH1:100m Ω internal low $R_{DS(ON)}$ MOSFETs
- $CH2{:}200m\Omega$ internal low $R_{DS(ON)}$ MOSFETs
- Fixed switching frequency:
 - CH1: 400KHz
 - CH2: 300KHz
- Flicker Free
- Compatible with most of electronic transformer
- RoHS Compliant and Halogen Free
- Compact package: SO8E

Applications

MR16

Typical Applications

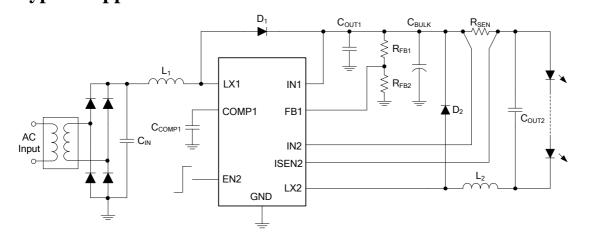


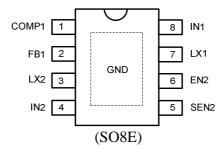
Figure 1. Schematic Diagram

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殷先生:13380368939 QQ: 719307610



Pinout (top view)



Top Mark: AQFxyz, (Device code: AQF, x=year code, y=week code, z=lot number code)

Pin Name	Pin Number	Pin Description			
COMP1	1	Compensation pin for CH1. Connect a capacitor from this pin to GND			
FB1	2	Feedback input and OVP input for CH1. The output voltage is within			
		$1.0*(R_{FB1}+R_{FB2})/R_{FB2}$ to $1.2*(R_{FB1}+R_{FB2})/R_{FB2}$			
LX2	3	Inductor node of CH2. Connect the switching node of the inductor to			
		this pin.			
IN2	4	Power supply input of CH2, also used as positive current sensing input			
SEN2	5	0.1(V)			
		Negative current sensing input of CH2. ILED(A) = $\frac{0.1(V)}{R_{SEN}(\Omega)}$			
		* '			
EN2	6	Enable control. Pull high to turn on CH2. Do not float. This pin can			
		also be used as dimming control. Apply a low frequency (<1kHz)			
		PWM signal for PWM dimming and a high frequency (>20kHz) PWM			
		signal for analog dimming.			
LX1	7	Inductor node of CH1. Connect an inductor between power input and			
		LX1 pin.			
IN1	8	Power supply input of CH1			
GND	Exposed	Ground pin			
	Paddle				

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SY8722A Rev.0.1



Electrical Characteristics

 $(V_{IN1} = V_{IN2} = 12V, T_A = 25^{\circ}C \text{ unless otherwise specified})$

Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
Input Voltage Range	V_{IN1}, V_{IN2}		4		30	V
CH1 Low Side Main FET RON	R _{DS(ON)1}			100		mΩ
CH2 Low Side Main FET RON	R _{DS(ON)2}			200		mΩ
CH1 Main FET Current Clamping	I _{CLMP, LOW}	Duty=0		1.3		A
Low Level						
CH1 Main FET Current Limit	I_{LIM1}	Duty=0		3		A
CH2 Main FET Current Limit	I_{LIM2}	Duty=0	2		3	A
CH1 Switching Frequency	Fsw1			400		KHz
CH2 Switching Frequency	Fsw2			300		KHz
Input UVLO Rising Threshold	$V_{\rm IN,UVLO}$				3.9	V
Input UVLO Hysteresis	$U_{VLO,HYS}$			0.2		V
FB1 Reference Voltage	V _{REF1}		0.97	1.0	1.03	V
CH2 Current Sense Limit	V _{IN2} -V _{SEN2}		96	100	104	mV
CH1 OVP Rising Threshold	$V_{FB1,OVP}$			1.2		V
CH1 OVP Hysteresis	$V_{FB1,HYS}$			150		mV
Thermal Shutdown Temperature	T_{SD}			150		°C

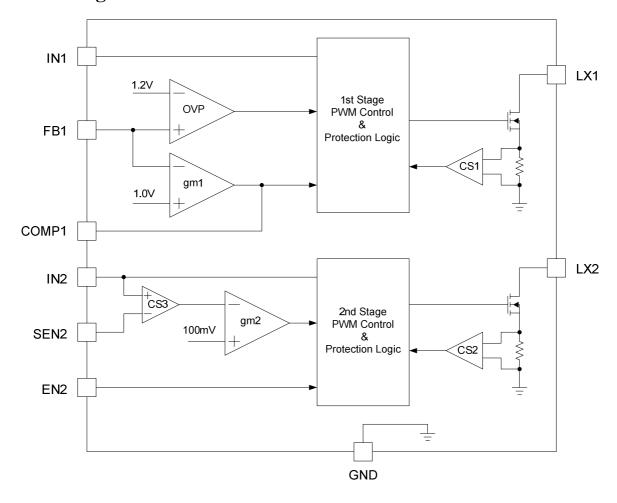
Note 1: Stresses beyond the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only. Functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note 2: θ JA is measured in the natural convection at $T_A = 25^{\circ}$ C on a low effective single layer thermal conductivity test board of JEDEC 51-3 thermal measurement standard.

Note 3: The device is not guaranteed to function outside its operating conditions



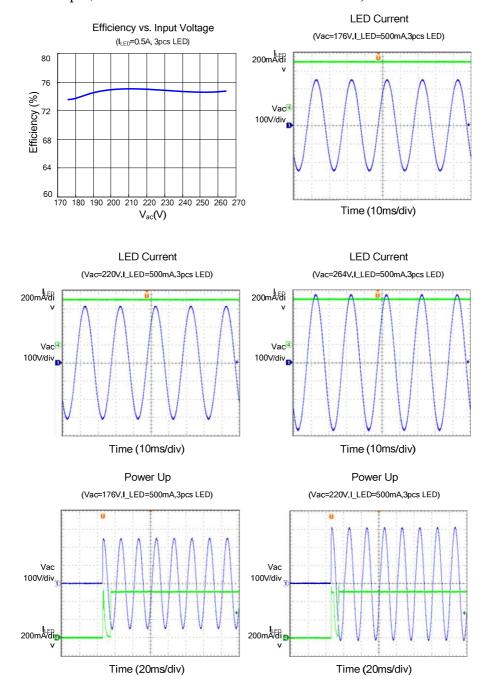
Block Diagram



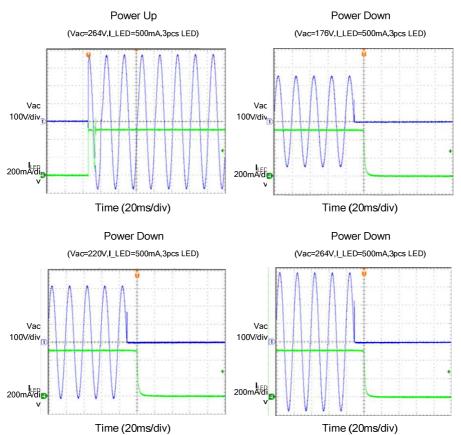


Typical Operating Characteristics total with ET-E60 elect

(176V~264V AC input, tested with ET-E60 electronic transformer)









Operation

SY8722A contains a Boost voltage regulator, and a floating Buck current regulator. The voltage regulator regulates the input to a setting voltage and provides power supply for the current regulator, while the current regulator provides constant current for LED loads

With integrated ultra low $R_{\rm DS(ON)}$ power switches and proprietary PWM control, this regulator IC can achieve the high efficiency and the high switch frequency simultaneously to minimize the external inductor and capacitor size, and thus achieving the minimum solution footprint.

Applications Information

Because of the high integration of SY8722A IC, the application circuit based on this IC is relatively simple. Only several external components are required.

Feedback resistor divider RfB1, and RfB2,:

Choose R_{FB1} and R_{FB2} to program the minimum output voltage of the Boost regulator. To minimize the power consumption, it is desirable to choose large resistance values for both R_{FB1} and R_{FB2} . A value of between 10k Ω and 1M Ω is highly recommended for both resistors. If $R_{FB2}{=}13.7k$ is chosen, then R_{FB1} can be calculated to be:

$$R_{FB1} = R_{FB2} \times (V_{RUS\ MIN} - 1)$$

 V_{BUS_MIN} is the minimum output voltage of Boost regulator. It should be higher than the maximum input. Once R_{FB1} and R_{FB2} are chosen, the maximum output voltage of the Boost regulator is its OVP voltage that can be calculated to be:

$$V_{\text{BUS_OVP}} = 1.2 \times (\frac{R_{\text{FB2}}}{R_{\text{FB1}}} + 1)$$

Current sense resistor Rsen:

Choose R_{SEN} to program the proper output current for the Buck regulator:

$$I_{LED}(A) = \frac{0.1(V)}{R_{SEN}(\Omega)}$$

Output capacitor Cout1, Cout2 and CBULK,:

The output capacitor C_{OUT1} and C_{OUT2} are selected to handle the output ripple noise requirements. For the best performance, it is recommended to use X7R or better grade ceramic capacitor greater than 1uF capacitance. C_{OUT1} is use to handle both output ripple of Boost regulator and input ripple of Buck regulator, the RMS current through the capacitor is relatively high. The RMS current rating of the capacitor should be considered.

The bulk capacitor is used to hold the bus voltage when the electronic transformer has no output. For most applications, it is recommended to use an aluminum electrolytic capacitor with greater than 220uF capacitance.

Compensation capacitor CCOMP,:

In applications powered by electronic transformer, the input voltage can change roughly in one cycle of AC power frequency. A 1uF ceramic capacitor connected from COMP1 pin to ground help to stabilize the control loop of the Boost regulator.

Output inductor L₁ and L₂:

It is very critical to select the Boost inductor for better efficiency and higher PF. With propriety control scheme, the Boost regulator is quite tolerant with difference inductance. So we can select the Boost inductor according to Buck output power.

For the Buck regulator, it is suggested to choose the ripple current to be about 40% of the maximum average inductor current. The inductance is calculated as:

$$L_{2} = \frac{V_{LED}(1 - V_{LED}/V_{BUS_OVP})}{F_{SW2} \times I_{LED} \times 40\%}$$

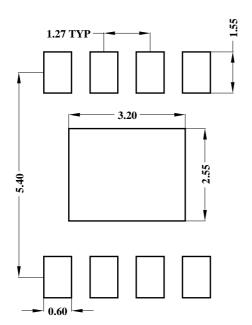
Where Fsw2 is the switching frequency of Buck regulator and I_{LED} is the LED current.

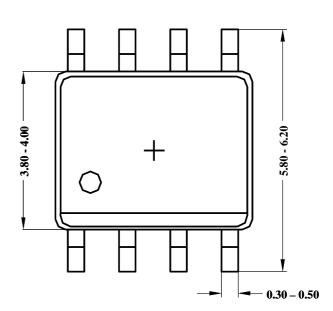
The saturation current rating of L₂ must be selected to be greater than the peak inductor current under full load conditions

$$I_{\text{SAT}} > I_{\text{LED}} + \frac{V_{\text{LED}} (1 \text{-} V_{\text{LED}} / V_{\text{BUS_OVP}})}{2 \cdot F_{\text{SW2}} \cdot L_2}$$

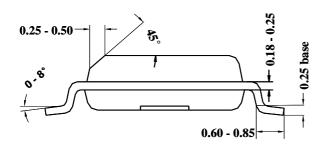


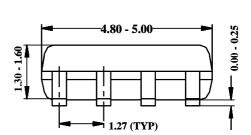
SO8E Package outline & PCB layout design





Recommended Pad Layout





Notes: All dimensions are in millimeters.
All dimensions don't include mold flash & metal burr.