



## 16-bit Serial-In/Parallel-Out Constant Current Driver

### Features

- . Fast output current control, the minimum output enable pulse width = 120ns
- . Current regulated output channels, constant current range: 5 – 60mA
- . Constant current source invariant to load voltage change
- . Excellent output current matching:

Current Skew		Conditions
Bit Skew	Chip Skew	
< ±3%	< ±6%	5mA < Iout < 60mA, output voltage >= 1.0V

- . All output current are adjusted through one external resistor
- . Built-in thermal protection function
- . Input interface:
  - SCT2026C: 5V CMOS level, Schmitt Triggered input
- . Supply voltage range: 4.5V~5.5V
- . Package: SOP24, SSOP24 and SDIP24

### Product Description

SCT2026 is designed as a current driver for the LED displays. It drives up to sixteen LED clusters with regulate constant current for uniform intensity.

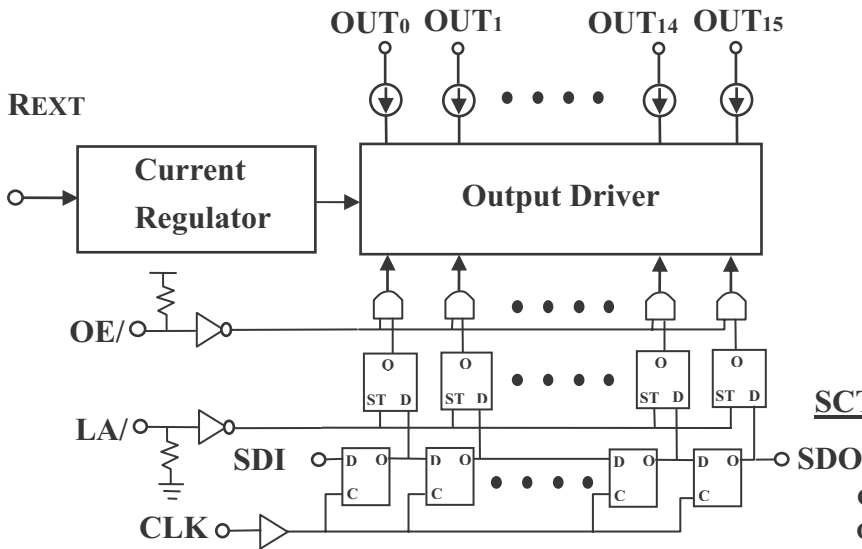
In applications, an external resistor is used to set the full-scale LED current from 5mA to 60mA. The SCT2026 guarantees each output can endure maximum 17V DC voltage stress. The built-in shift registers and data latches making the SCT2026 effective solution in driving LED display. Since the serial data input rate at can reach to 25MHz, the SCT2026 will satisfy system which needs high volume data transmission to control the LED display.

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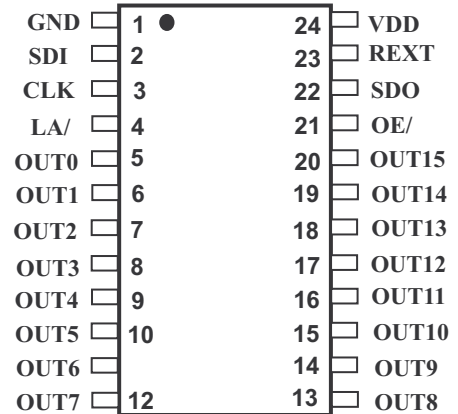
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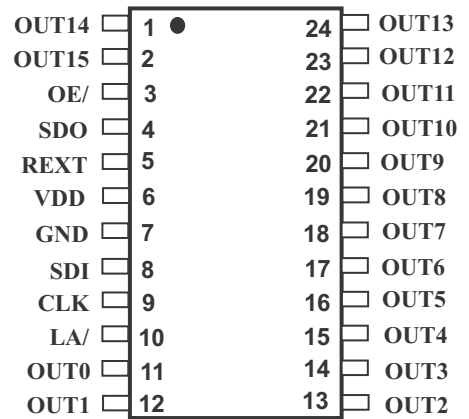
## Block Diagram



## Pin Configuration



### SCT2026CSOG/CSSG/CSTG/CSDG



### SCT2026CSAG






## Ordering information

Part Number	Marking	Package	Remark
SCT2026CSOG	SCT2026CSOG	Pb free SOP24	5V CMOS input
SCT2026CSSG	SCT2026CSSG	Pb free SSOP24	5V CMOS input
SCT2026CSAG*	SCT2026CSAG	Pb free SSOP24	5V CMOS input
SCT2026CSTG	SCT2026CSTG	Pb free SOP24-1.0	5V CMOS input
SCT2026CSDG	SCT2026CSDG	Pb free SDIP24	5V CMOS input

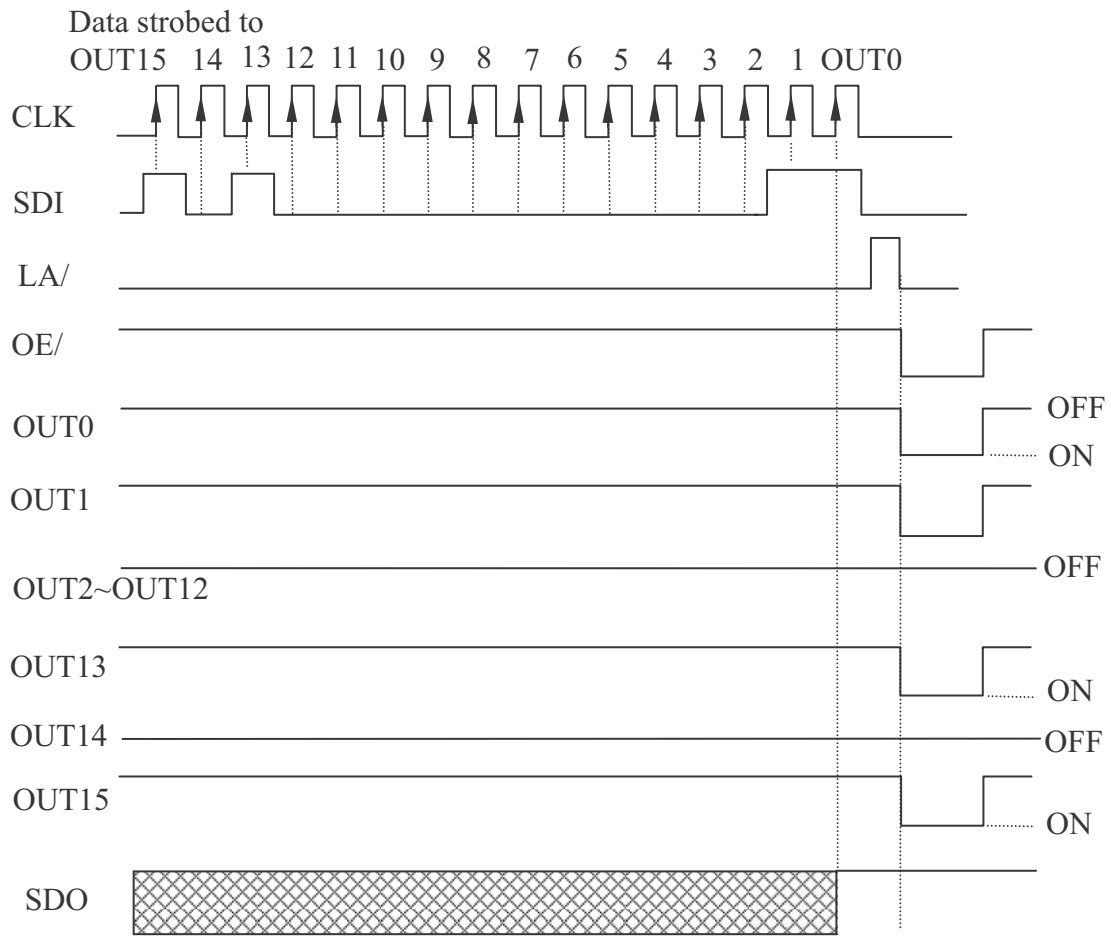
## Terminal Description

Pin No.	Pin Name	Function
1	GND	Ground terminal.
2	SDI	Serial input terminal of data shift register.
3	CLK	Clock input terminal of shift register, data is sampled at the rising edge of CLK.
4	LA/	Input terminal of data strobe. Data is latched when LA/ is low. And data on shift register goes through when LA/ is high.
5 ~ 20	OUT <sub>0</sub> ~ OUT <sub>15</sub>	Output terminals with constant current.
21	OE/	Input terminal of output enable signal. Output is enabled when OE/ is low.
22	SDO	Output terminal of serial-data output to the SDI of next SCT2026.
23	R <sub>EXT</sub>	Input terminal used to connect an external resistor for setting up all output current.
24	V <sub>DD</sub>	Supply voltage terminal.

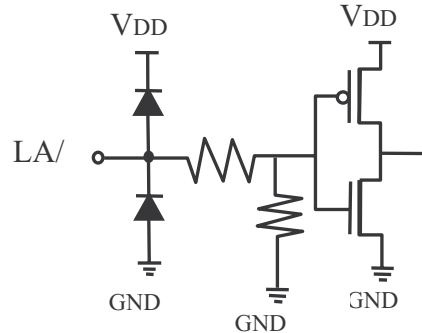
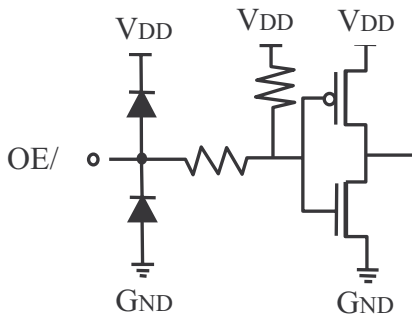
## Truth Table

CLK	LA/	OE/	SDI	OUT <sub>0</sub> ~ OUT <sub>15</sub>	SDO
	H	L	D <sub>n</sub>	D <sub>n</sub> D <sub>n-1</sub> ---- D <sub>n-14</sub> D <sub>n-15</sub>	D <sub>n-15</sub>
	L	L	D <sub>n+1</sub>	No change	D <sub>n-14</sub>
	H	L	D <sub>n+2</sub>	D <sub>n+2</sub> D <sub>n</sub> ---- D <sub>n-12</sub> D <sub>n-13</sub>	D <sub>n-13</sub>
	X	L	D <sub>n+3</sub>	D <sub>n+2</sub> D <sub>n</sub> ---- D <sub>n-12</sub> D <sub>n-13</sub>	D <sub>n-13</sub>
	X	H	D <sub>n+3</sub>	Off	D <sub>n-13</sub>

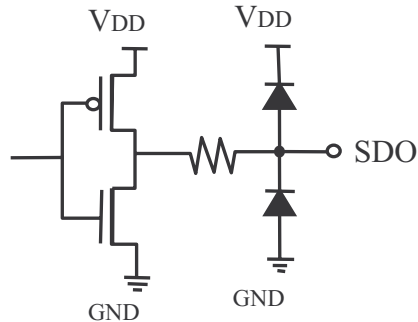
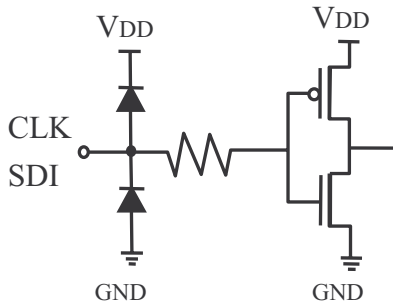
**Timing Diagram**



**Equivalent Circuits of Inputs (1)**



**Equivalent Circuits of Inputs (2)**



**Maximum Ratings** (Ta = 25 °C)

Characteristic	Symbol	Rating	Unit
Supply voltage	V <sub>DD</sub>	4.0 ~ 7.0	V
Input voltage	V <sub>IN</sub>	-0.2 ~ V <sub>DD</sub> +0.2	V
Output current	I <sub>OUT</sub>	80	mA/Channel
Output voltage	V <sub>OUT</sub>	-0.2 ~ 17.0	V
Total GND terminals current	I <sub>GND</sub>	1300	mA
Power Dissipation	P <sub>D</sub>	1.25(Free Air) 1.78(on PCB)	W
Thermal Resistance	R <sub>TH(j-a)</sub>	104(Free Air) 70(on PCB)	°C /W
Operating temperature	T <sub>OPR</sub>	-40~+85	°C
Storage temperature	T <sub>STG</sub>	-55~+150	°C

## Recommended Operating Conditions

(Ta=-40 to 85 °C unless otherwise noted)

Characteristic	Symbol	Condition	Min.	Typ.	Max.	Unit
Supply voltage	$V_{DD}$	-	4.5	5.0	5.5	V
Output voltage	$V_{OUT}$	OUT0 ~ OUT15	1.0	-	17	V
Output current	$I_{OUT}$	DC test circuit	5	-	60	mA
Input voltage (SCT2026C)	$V_{IH}$	Input signals	$0.7V_{DD}$	-	$V_{DD}$	V
	$V_{IL}$	Input signals	0	-	$0.3V_{DD}$	V
OE/ pulse width	$t_w$	$V_{DD}=4.5\sim 5.5V$	80	-	-	ns

## Electrical Characteristics

(VDD=5.0V, Ta=25°C unless otherwise noted)

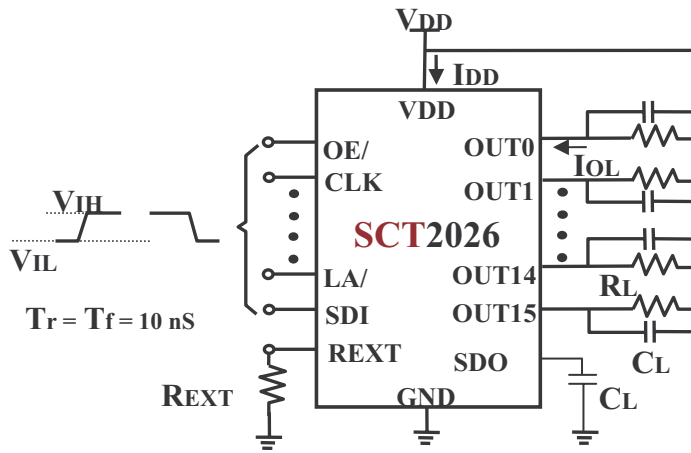
Characteristic	Symbol	Condition	Min.	Typ.	Max.	Unit	
Input voltage (SCT2026C)	$V_{IH}$		$0.7V_{DD}$	-	$V_{DD}$	V	
	$V_{IL}$		0	-	$0.3V_{DD}$	V	
Output leakage current	$I_{OL}$	$V_{OH} = V_{DD} = 7V$	-	-	0.5	$\mu A$	
Output current	$I_{OUT}$	$V_{OUT}=1.0V$ $R_{EXT}=900 \Omega$	-	21	-	mA	
Current bit skew	$dI_{OUT}$	$I_{OL}=21mA$ $R_{EXT}=900 \Omega$ $V_{OUT}=1.0V$	-	$\pm 1$	$\pm 3$	%	
$I_{OUT}$ vs. supply voltage regulation	$\%/dV_{DD}$	$4.5V < V_{DD} < 5.5V$ $V_{OUT} > 1.0V$	-	-	$\pm 2$	%/V	
$I_{OUT}$ vs. output voltage regulation	$\%/dV_{OUT}$	$1.0V < V_{OUT} < 17.0V$ $I_{OL}=30mA, V_{DD} = 5V$	-	-	$\pm 2$	%/V	
Supply current	OFF	$I_{DD(off) 1}$	$R_{EXT} = \text{Open}, V_{DD} = 5V$ $OUT0\sim OUT15=Off$		-	12	mA
		$I_{DD(off) 2}$	$R_{EXT} = 900, V_{DD} = 5V$ $OUT0\sim OUT15=Off$		-	13	
	ON	$I_{DD(on)}$	$R_{EXT} = 900, V_{DD} = 5V$ $OUT0\sim OUT15=On$		-	13	

**Switching Characteristics**

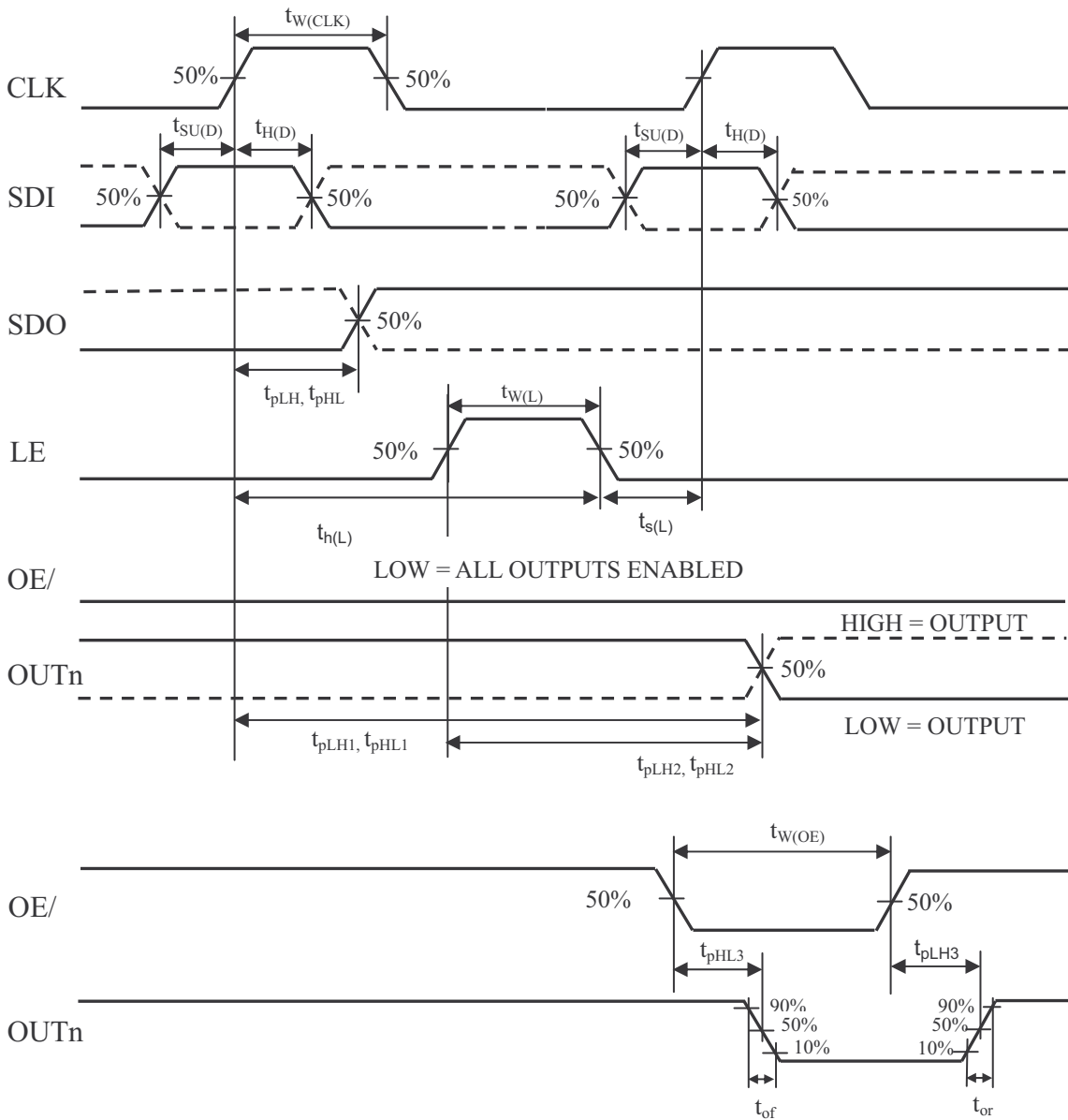
(VDD=5.0V, Ta=25°C unless otherwise noted)

Characteristic		Symbol	Condition	Min.	Typ.	Max.	Unit		
Propagation Delay Time (“L” to “H”)	CLK - OUTn	$t_{pLH1}$	$V_{DD} = 5.0\text{ V}$ $V_{LED} = V_{DD}$ $V_{IH} = V_{DD}$ $V_{IL} = \text{GND}$ $R_{EXT} = 900\ \Omega$ $R_L = 150\ \Omega$ $C_L = 10\text{ pF}$	-	30	60	ns		
	LA/ - OUTn	$t_{pLH2}$		-	100	150	ns		
	OE/ - OUTn	$t_{pLH3}$		-	50	100	ns		
	CLK - SDO	$t_{pLH}$		15	20	-	ns		
Propagation Delay Time (“H” to “L”)	CLK - OUTn	$t_{pHL1}$		$V_{DD} = 5.0\text{ V}$ $V_{LED} = V_{DD}$ $V_{IH} = V_{DD}$ $V_{IL} = \text{GND}$ $R_{EXT} = 900\ \Omega$ $R_L = 150\ \Omega$ $C_L = 10\text{ pF}$	-	40	60	ns	
	LA - OUTn	$t_{pHL2}$			-	100	150	ns	
	OE/ - OUTn	$t_{pHL3}$			-	30	60	ns	
	CLK - SDO	$t_{pHL}$			15	20	-	ns	
Pulse Width	CLK	$t_{w(\text{CLK})}$			$V_{DD} = 5.0\text{ V}$ $V_{LED} = V_{DD}$ $V_{IH} = V_{DD}$ $V_{IL} = \text{GND}$ $R_{EXT} = 900\ \Omega$ $R_L = 150\ \Omega$ $C_L = 10\text{ pF}$	20	-	-	ns
	LA/	$t_{w(\text{L})}$				20	-	-	ns
	OE/	$t_{w(\text{E})}$				80	-	-	ns
Hold Time for LA/		$t_{h(\text{L})}$				$V_{DD} = 5.0\text{ V}$ $V_{LED} = V_{DD}$ $V_{IH} = V_{DD}$ $V_{IL} = \text{GND}$ $R_{EXT} = 900\ \Omega$ $R_L = 150\ \Omega$ $C_L = 10\text{ pF}$	5	-	-
Setup Time for LA/		$t_{s(\text{L})}$	5				-	-	ns
Output Rise Time of Iout		$t_{or}$	-				10	20	ns
Output Fall Time of Iout		$t_{of}$	-				10	20	ns

**Test Circuit for Switching Characteristics**

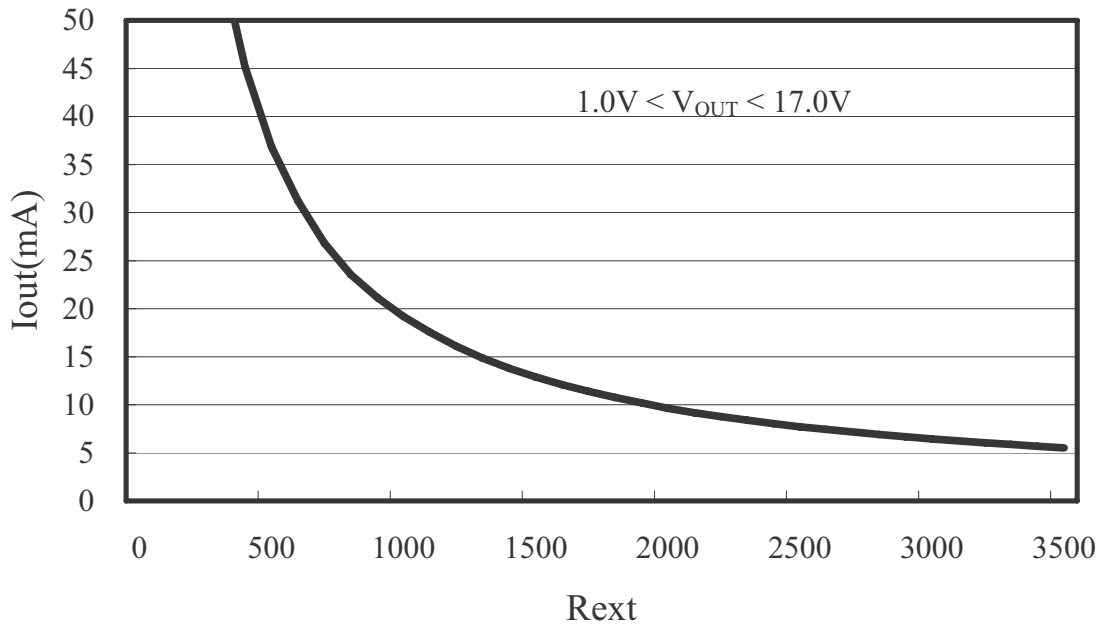


**Timing Waveform**



## Adjusting Output Current

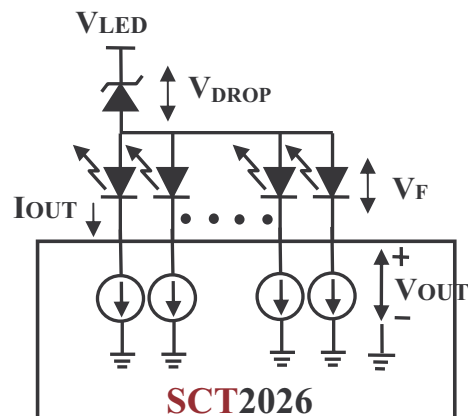
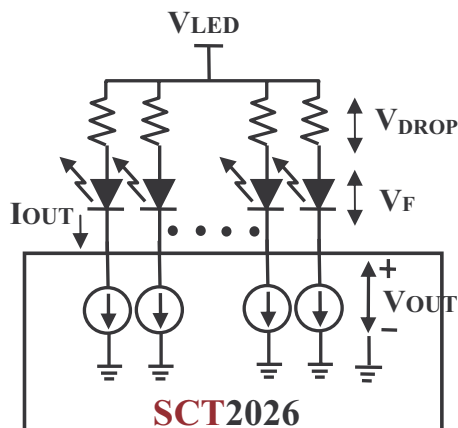
All SCT2026's output current ( $I_{OUT}$ ) are set by one external resistor at pin  $R_{EXT}$ . The relationship between  $I_{OUT}$  and resistance  $R_{EXT}$  is shown as the following figure.



Also, when SCT2026's output voltage is set between 1.0 Volt and 17.0 Volt, the output current can be estimated approximately by:  $I_{OUT} = 30(620 / R_{EXT})$  (mA). Thus the output current are all set to be about 21mA at  $R_{EXT} = 900 \Omega$ .

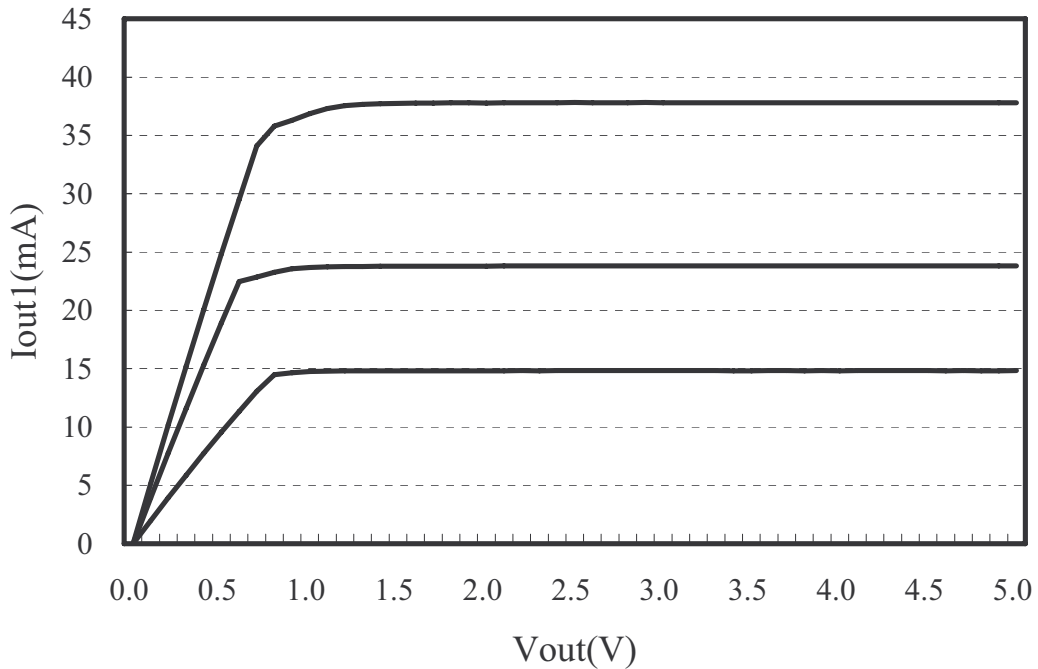
## Load Supply Voltage ( $V_{LED}$ )

SCT2026 can operate very well only when  $V_{OUT}$  ranging from 1.0V to 17.0V. So it is recommended to use the lowest possible supply voltage or set a voltage reducer to reduce the  $V_{OUT}$  voltage. A voltage reducer lets  $V_{OUT} = V_{LED} - V_{DROP} - V_F$ . Resistors or Zener diode can be used in the applications as shown in the following figures.



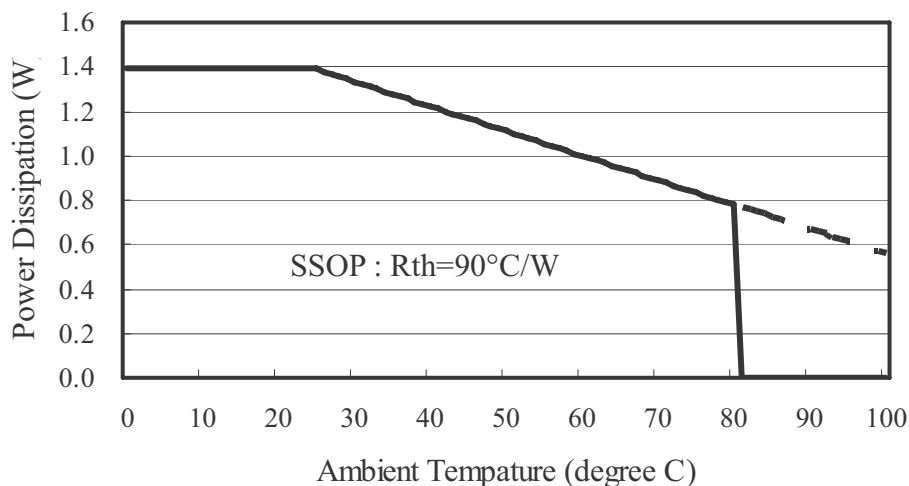
### Constant Current

The current characteristic of output stage is flat. The output current can be kept constant regardless of the variations of LED forward voltage when  $V_{OUT} > 1.0V$ . The relationship between  $I_{OUT}$  and  $V_{OUT}$  is shown as :



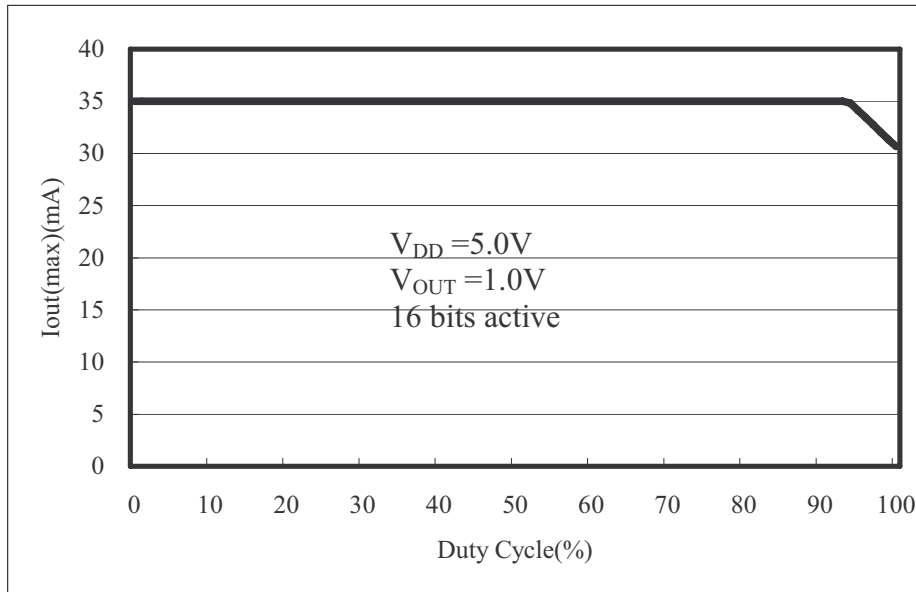
### Power Dissipation

The power dissipation ( $P_D$ ) of a semiconductor chip is limited by its package and ambient temperature. The maximum allowable power dissipation ( $P_D$ ) is determined as  $P_D(max) = (T_j - T_a) / R_{th(j-a)}$  where  $T_j$ : the chip junction temperature,  $T_a$ : ambient temperature,  $R_{th(j-a)}$ : thermal resistance. For SSOP packages, the relationship between  $P_D$  and  $T_a$  is shown as the following figure.



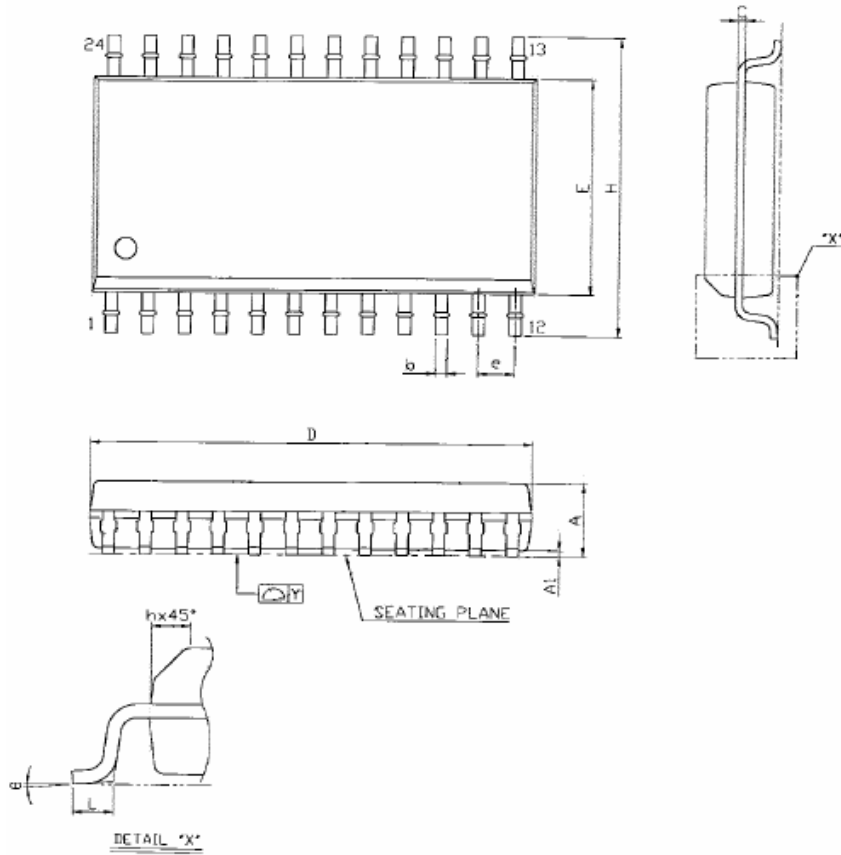
## Maximum Output Current

In practical case, the SCT2026 turn on the output in partial period. So the actual package power dissipation is  $P_D(\text{act}) = (I_{DD} \cdot V_{DD}) + (\# \text{ outputs} \cdot I_{OUT} \cdot V_{OUT} \cdot \text{Duty})$ . Therefore, to keep  $P_D(\text{act}) \leq P_D(\text{max})$ , the allowed maximum output current be calculated from the equation:  $I_{OUT} = (P_D - I_{DD} \cdot V_{DD}) / (\# \text{ outputs} \cdot V_{OUT} \cdot \text{Duty})$ . So the relationship between  $I_{OUT}(\text{max})$  and  $T_a$  is shown as the following figure:



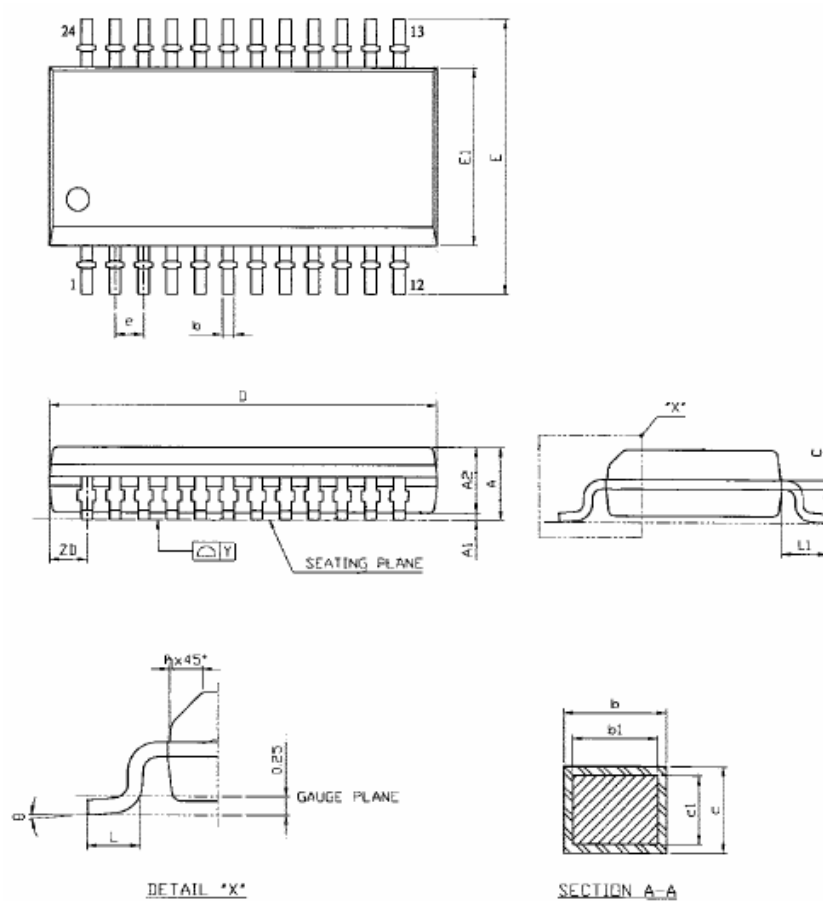
**Package Dimension**

SOP24



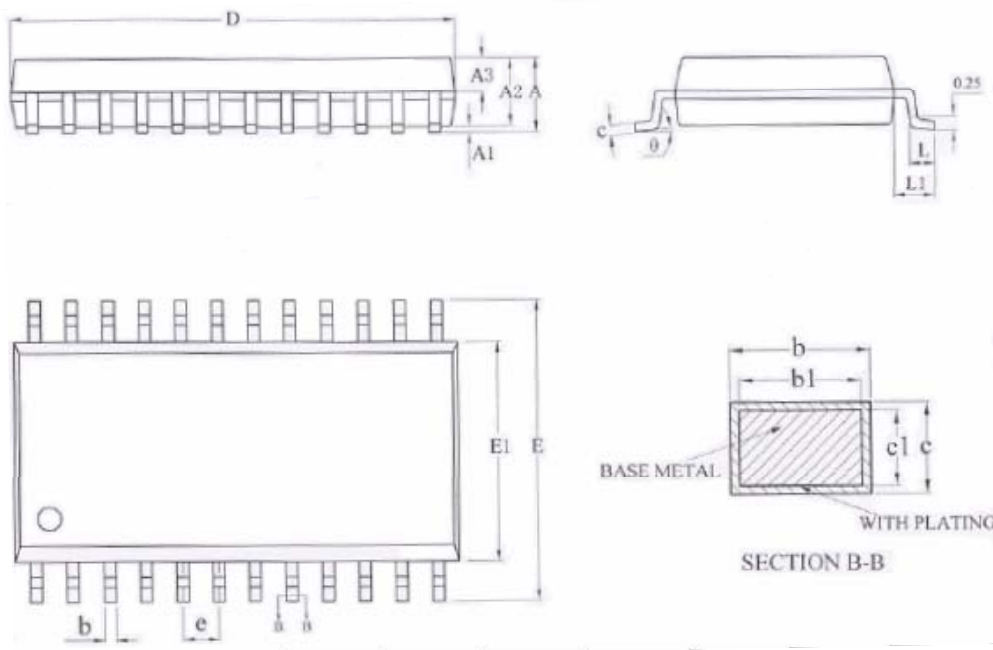
SYMBOL	DIMENSION (mm)			DIMENSION (mil)		
	MIN	NOM	MAX	MIN	NOM	MAX
A	2.36	2.54	2.64	93	100	104
A1	0.10	0.20	0.30	4	8	12
b	0.35	0.406	0.48	14	16	19
c	0.23	0.254	0.31	9	10	12
D	15.20	15.29	15.60	598	602	614
E	7.40	7.50	7.60	291	295	299
e	1.27 BSC			50 BSC		
H	10.00	10.31	10.65	394	406	419
h	0.25	0.66	0.75	10	26	30
L	0.51	0.76	1.02	20	30	40
Y			0.075			3
$\theta$	0°		8°	0°		8°

SSOP24



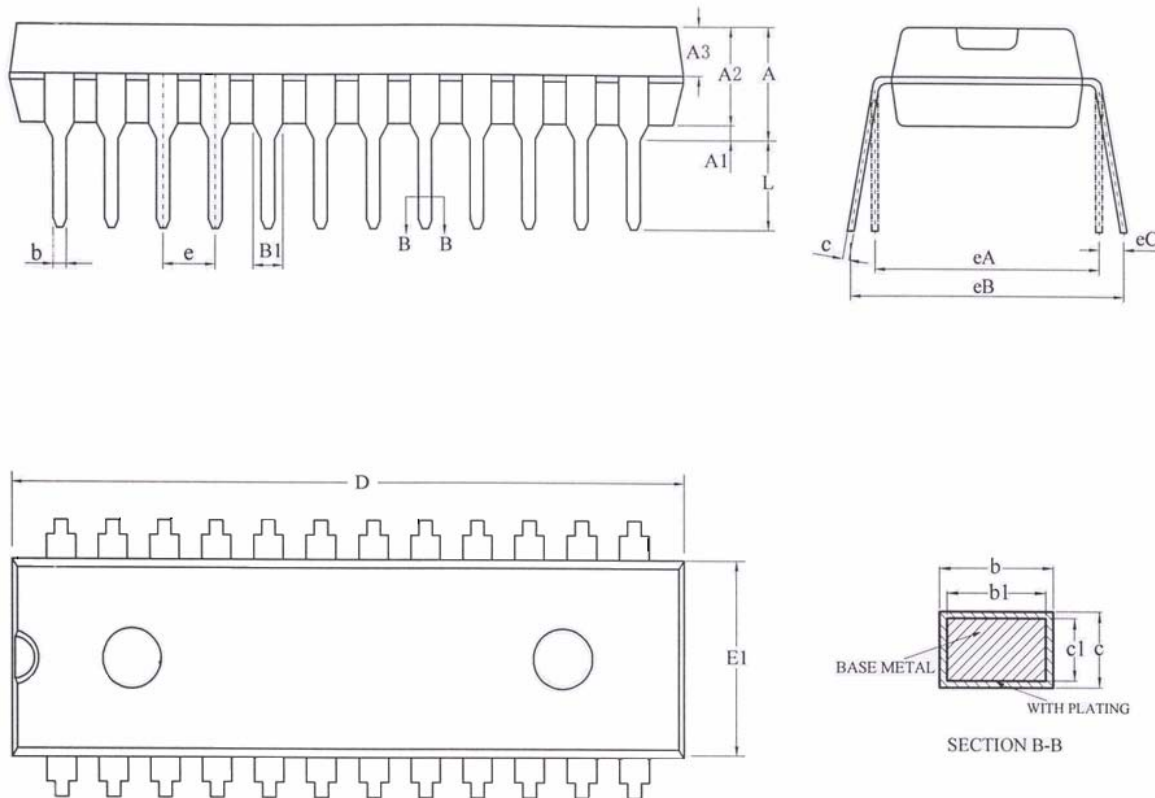
SYMBOL	DIMENSION (mm)			DIMENSION (mil)		
	MIN	NOM	MAX	MIN	NOM	MAX
A	1.35	1.60	1.75	53	63	69
A1	0.10	0.15	0.25	4	6	10
A2			1.50			59
b	0.20		0.30	8		12
b1	0.20	0.254	0.28	8	10	11
c	0.18		0.25	7		10
c1	0.18	0.203	0.23	7	8	9
D	8.56	8.66	8.74	337	341	344
E	5.80	6.00	6.20	228	236	244
E1	3.80	3.90	4.00	150	154	157
e	0.635 BSC			25 BSC		
h	0.25	0.42	0.50	10	17	20
L	0.40	0.635	1.27	16	25	50
L1	1.00	1.05	1.10	39	41	43
ZD	0.838 REF			33 REF		
Y			0.10			4
θ	0°		8°	0°		8°

SSOP24-1.0



SYMBOL	DIMENSION (mm)			DIMENSION (mil)		
	MIN	NOM	MAX	MIN	NOM	MAX
A	-	-	2.20	-	-	87
A1	0.10	0.20	0.30	4	8	12
A2	1.60	1.80	2.00	63	71	79
A3	0.62	0.82	0.92	24	32	36
b	0.39	-	0.47	15	-	19
b1	0.38	0.40	0.43	15	16	17
c	0.15	-	0.20	6	-	8
c1	0.14	0.15	0.16	5.5	6	6.5
D	12.80	13.00	13.20	504	512	520
E	7.70	7.90	8.10	303	311	319
E1	5.80	6.00	6.20	228	236	244
e	1.00 BSC			39 BSC		
L	0.35	0.45	0.55	14	18	22
L1	0.95 BSC			37 BSC		
θ	0°	-	8°	0°	-	8°

## SDIP24



SYMBOL	DIMENSION (mm)			DIMENSION (mil)		
	MIN	NOM	MAX	MIN	NOM	MAX
A	3.60	3.80	4.00	142	150	157
A1	0.30	-	-	12	-	-
A2	3.10	3.30	3.50	122	130	138
A3	1.42	1.52	1.62	56	60	64
b	0.44	-	0.53	17	-	21
b1	0.43	0.46	0.48	17	18	19
B1	1.00 BSC			39 BSC		
c	0.25	-	0.31	10	-	12
c1	0.24	0.25	0.26	9	10	11
D	22.70	22.90	23.10	894	902	909
E1	6.40	6.60	6.80	252	260	268
e	1.778 BSC			70 BSC		
eA	7.62 BSC			300 BSC		
eB	7.62	-	9.50	300	-	374
eC	0	-	0.94	0	-	37
L	3.00	-	-	118	-	-